

Coordinate Changes for Integrals

IDEA: In Calculus I you used coordinate changes to solve

$$\textcircled{1} \int_{x=0}^5 x e^{x^2} dx \quad \begin{array}{l} u = x^2 \leftarrow \text{coordinate change,} \\ du = 2x dx \text{ Parametrizes } \mathbb{R} \\ \uparrow \\ \text{necessary differential composition} \end{array}$$

$\textcircled{2}$ Polar coordinate change

$$\iint_R e^{x^2+y^2} dA \rightarrow \iint_R r e^{r^2} dA \quad \begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

We want a more general way to compute these coordinate changes for integrals (make differential equations easier)

Answer: Jacobians!

Def// Jacobian of a coordinate change

$$\begin{cases} x_1 = x_1(u_1, u_2, \dots, u_n) \\ x_2 = x_2(u_1, u_2, \dots, u_n) \\ \vdots \\ x_n = x_n(u_1, u_2, \dots, u_n) \end{cases}$$

$$\frac{d(x_1, x_2, \dots, x_n)}{d(u_1, u_2, \dots, u_n)} = \begin{bmatrix} \frac{\partial x_1}{\partial u_1} & \frac{\partial x_1}{\partial u_2} & \dots & \frac{\partial x_1}{\partial u_n} \\ \frac{\partial x_2}{\partial u_1} & \frac{\partial x_2}{\partial u_2} & \dots & \frac{\partial x_2}{\partial u_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_n}{\partial u_1} & \frac{\partial x_n}{\partial u_2} & \dots & \frac{\partial x_n}{\partial u_n} \end{bmatrix}$$

Example: Jacobian of polar coordinate change is

$$\frac{d(x, y)}{d(r, \theta)} = \det \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{bmatrix}$$

$$= \cos \theta (r \cos \theta) - (\sin \theta (-r \sin \theta)) = r(\cos^2 \theta + \sin^2 \theta) = r$$

NB: if we reverse order of (r, θ) , we get

$$\frac{d(x,y)}{d(\theta,r)} = \det \begin{bmatrix} dx/d\theta & dy/d\theta \\ dx/dr & dy/dr \end{bmatrix} = \det \begin{bmatrix} -r \sin \theta & \cos \theta \\ r \cos \theta & \sin \theta \end{bmatrix}$$

$$= -r \sin \theta \cos \theta - r \cos \theta \sin \theta$$

$$= -r(\sin^2 \theta + \cos^2 \theta) = -r$$

Def// The (unsigned) Jacobian of a transformation is simply

$$\left| \frac{d(x_1, x_2, \dots, x_n)}{d(u_1, u_2, \dots, u_n)} \right|$$

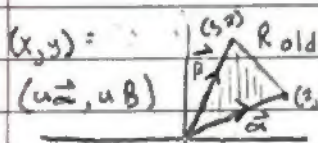
Prop: Let $f(x_1, x_2, \dots, x_n)$ be a function continuous on R and

$$\begin{cases} x_1 = x_1(u_1, \dots, u_n) \\ \vdots \\ x_n = x_n(u_1, \dots, u_n) \end{cases}$$

Change by diff. fractions

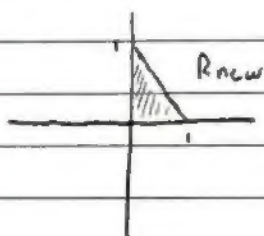
$$\int_{R_{old}} f(x_1, \dots, x_n) dV_{old} = \int f(x_1(u_1, \dots, u_n), \dots, x_n(u_1, \dots, u_n)) \cdot \left| \frac{d(x_1, \dots, x_n)}{d(u_1, \dots, u_n)} \right| dV_{new}$$

Example: compute $\iint_R (x-2y) dA$ for R the triangle w vertices $(0,0), (1,2), (2,1)$



Sol 1: using cartesian, split region and compute (do this on your own)

Sol 2: using a simple transformation



$$(u,v) = (1,0) \rightarrow (x,y) = (2,1)$$

$$(u,v) = (0,1) \rightarrow (x,y) = (1,2)$$

$$\begin{cases} x = 2u + v \\ y = u + 2v \end{cases}$$

check that first triangle maps to second

Moreover, $R_{\text{new}} = \{(u, v) : 0 \leq u \leq 1, 0 \leq v \leq 1-u\}$

$$\frac{d(x, y)}{d(u, v)} = \det \begin{bmatrix} dx/du & dx/dv \\ dy/du & dy/dv \end{bmatrix} = 4 - 1 = 3$$

$$\therefore \iint_R (x-2y) dA_{old} = \iint_{R_{\text{new}}} (2u+v) - 2(ut^2) \cdot 3 dA_{\text{new}}$$

$$= 3 \int_{u=0}^1 \int_{v=0}^{1-u} -3v du dv$$

$$= -9 \int_0^1 \left(\frac{1}{2} v^2 \right)_{v=0}^{1-u} du = -9/2 \int_0^1 (1-u)^2$$

$$= 9/2 \left(\frac{1}{3} \left[(1-u)^3 \right]_{u=0}^1 \right) = 3/2 (-1) = \boxed{-3/2}$$

Generalizing Polar Coordinates To 3-space

I) Cylindrical Coordinates

IDEA: Parametrize one plane w/ polar coordinates,

leave orthogonal axes alone...

in particular, this coordinate change is

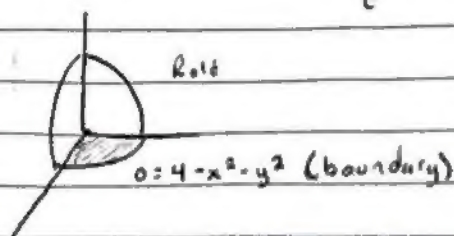
$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$

$$\text{differential: } \frac{d(x, y, z)}{d(r, \theta, z)} = \begin{bmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{aligned} \cos \theta (r \cos \theta) + r \sin \theta (\sin \theta) + 0 (r \cos^2 \theta - r \sin^2 \theta) \\ = r (\cos^2 \theta + \sin^2 \theta) \\ = r \end{aligned}$$

Takeaway: $dA_{\text{cylindrical}} = r dA_{\text{polar}}$ for all cylindrical transformations

Example: Compute $\iiint_E (x+y+z) dv$, E in first octant, paraboloid $4-x^2-y^2=z$



Sol: parametrize in cylindrical coordinates

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases} \quad R_{cyl} = \begin{cases} (r, \theta, z) : 0 \leq \theta \leq \pi/2 \\ 0 \leq z \leq 4-r^2 \end{cases}$$

$$\therefore \iiint_E (x+y+z) dv = \iiint_{R_{cyl}} (r \cos \theta + r \sin \theta + z) r \, dv$$

$$= \int_0^2 \int_0^{\pi/2} \int_0^{4-r^2} (r \cos \theta + r \sin \theta + z) r \, dz \, d\theta \, dr$$

$$= \int_0^2 \int_0^{\pi/2} \left[r \sin \theta - r \cos \theta + \theta z \right]_{z=0}^{\pi/2} d\theta \, dr$$

$$= \int_0^2 \int_0^{\pi/2} \left(2r^2 + \frac{\pi}{2} r z \right) d\theta \, dr$$

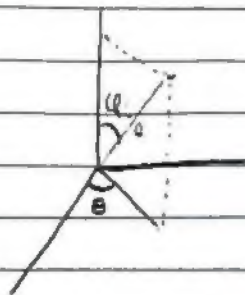
$$= \int_0^2 \left(2r^2 z + \frac{\pi}{4} r z^2 \right) \Big|_0^{4-r^2} dr$$

$$= \int_0^2 \left(8r^2 - 2r^4 + \frac{\pi}{4} (16r - 8r^3 + r^5) \right) dr$$

$$= \left[\frac{8}{3} r^3 - \frac{2}{5} r^5 + \frac{\pi}{4} \left(16r^2 - 2r^4 + \frac{1}{6} r^6 \right) \right]_{r=0}^2$$

$$= 64/3 - 64/5 + \pi 8/3$$

II Spherical coordinates: Every point in \mathbb{R}^3 lies on a sphere



we parametrize via

ρ = distance from (x, y, z) to origin

θ = angle from x axis to point (x, y, z)

ϕ = angle from y axis to point (x, y, z)



$$\begin{cases} x = \rho \cos \theta \rightarrow \rho \sin(\phi) \cos \theta \\ y = \rho \sin \theta \rightarrow \rho \sin(\phi) \sin \theta \\ z = \rho \cos(\phi) \end{cases}$$